

Distributed Resolution for Expressive Ontology Networks

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MANNHEIM

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Problem

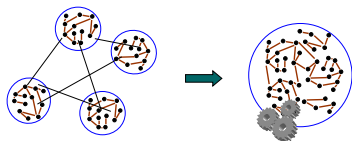
Reasoning on Interlinked Description Logic Ontologies

Common Approach: Merge

Problem

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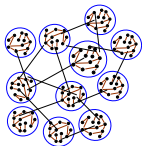
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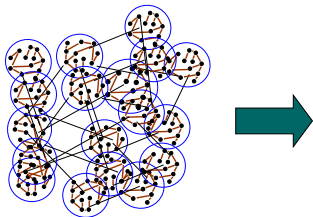
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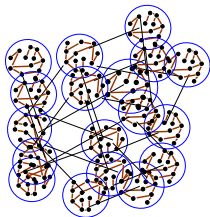
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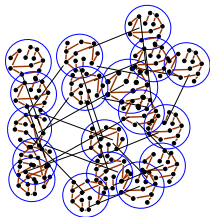
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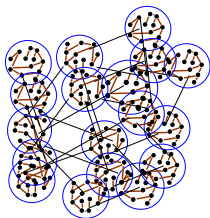
- Load ontology



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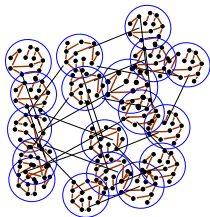
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- Load ontology
- Query runtime

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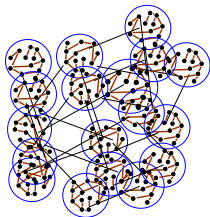
Standard Solution:

- Take advantage of specific structure

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Problem:

- Load ontology
- Query runtime

Standard Solution:

- Take advantage of specific structure
- Use incomplete reasoning methods

Related Work

Approaches

- DRAGO (C-OWL)
- MARVIN (RDF)
- Partition Based Reasoning (FOL)
- Distributed EL (Polynomial DL subset)
- Distributed A-box

Limitations

- Severe limitations on links (no subsumption between ontologies)
- FOL approaches not efficient for DL (FOL is not decidable)
- Limited expressivity
- Restrictions on distribution

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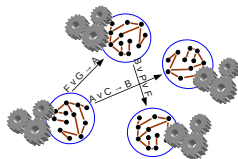
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Reasoning on Large DL Ontologies

Idea



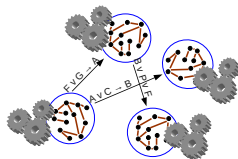
- Keep ontologies distributed
- Distribute computation load across several reasoners
- Every reasoner processes a small local set of axioms
- Axioms are sent to other reasoners if necessary

Goal

- Completeness and termination for expressive DL
- No restriction on link axioms
- No restriction on distribution
- Performance

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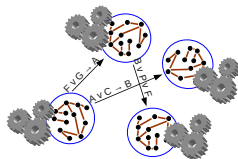
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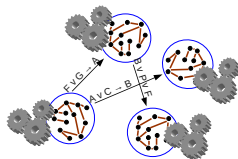
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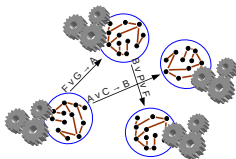
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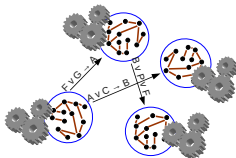
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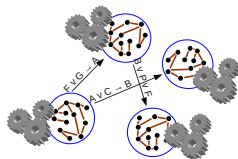
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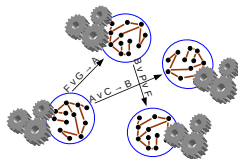
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Distributed Resolution Reasoning

Outline

- Local reasoning method
- Communication strategy
- Experiments

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Distributed Reasoning

Standard Description Logic Reasoning: Tableaux

- Extensively investigated and optimized for DL
- No efficient distribution known

Alternative: Resolution

- Extensively investigated for first order logic.
- Successfully applied to DL
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Preliminaries: The description logic \mathcal{ALCHIQ}

Translating DL Axioms to clauses

$$A \sqsubseteq B \quad \neg A(x) \vee B(x)$$

$$A \sqsubseteq B \sqcap C \quad \neg A(x) \vee B(x), \neg A(x) \vee C(x)$$

$$A \sqsubseteq B \sqcup C \quad \neg A(x) \vee B(x) \vee C(x)$$

$$A \sqsubseteq \exists r.B \quad \neg A(x) \vee r(x, f(x)), \neg A(x) \vee B(f(x))$$

$$A \sqsubseteq \forall r.B \quad \neg A(x) \vee \neg r(x, y) \vee B(y)$$

$$A \sqsubseteq \exists_{\leq n} r.B \quad \neg A(x) \vee \neg r(x, y_i) \vee y_i = y_j \vee \neg B(y_i) \\ i = 1..n+1 \quad j = 1..i-1$$

$$A \sqsubseteq \exists_{\geq n} r.B \quad \neg A(x) \vee r(x, f_i(x)), \neg A(x) \vee f_i(x) \neq f_j(x), \neg A(x) \vee B(f_i(x)) \\ i = 1..n \quad j = 1..i-1$$

$$r \sqsubseteq s \quad \neg r(x, y) \vee s(x, y)$$

$$r \equiv \text{Inv}(s) \quad \neg r(x, y) \vee s(y, x), \neg s(x, y) \vee r(y, x)$$

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$$\boxed{\text{GlobalCompany} \sqsubseteq \exists_{\geq 2} \text{situatedIn.Continent}}$$

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Resolution

Ordered Resolution

$$\frac{C(x) \vee A(x) \quad D(y, f(y)) \vee \neg A(f(y))}{C(f(y)) \vee D(y, f(y))} \quad x \rightarrow f(y)$$

- Literals are ordered (based on symbol precedence), unified literals have to be maximal
- Complete and terminates for *ALC^HI*
- Problem: no support for equalities (cardinality restrictions)

Basic Superposition (Bachmair et al. 1995)

$$\frac{C(x) \vee f(x) = g(x) \quad D(y, f(y)) \vee P(f(y))}{C(y) \vee D(y, f(y)) \vee P(g(y))}$$

- Extension of ordered resolution to deal with equalities
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Basic Superposition

$$\text{Positive superposition} \quad \frac{(C \vee s \approx t) \cdot \rho \quad D \vee (w \approx v) \cdot \rho}{(C \vee D \vee w[t]_p \approx v) \cdot \theta}$$

where

- 1 σ is the most general unifier of $s\rho$ and $w\rho|_p$ and $\theta = \rho\sigma$
- 2 $t\theta \not\approx s\theta$ and $v\theta \not\approx w\theta$
- 3 in $(C \vee s \approx t) \cdot \theta$ nothing is selected and $(s \approx t) \cdot \theta$ is strictly maximal
- 4 in $D \vee (w \approx v) \cdot \theta$ nothing is selected and $(w \approx v) \cdot \theta$ is strictly maximal
- 5 $w|_p$ is not a variable.
- 6 $s\theta \approx t\theta \not\approx w\theta \approx v\theta$

$$\text{Negative superposition} \quad \frac{(C \vee s \approx t) \cdot \rho \quad D \vee (w \not\approx v) \cdot \rho}{(C \vee D \vee w[t]_p \not\approx v) \cdot \theta}$$

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- 2 $t\theta \not\approx s\theta$ and $v\theta \not\approx w\theta$
- 3 in $(C \vee s \approx t) \cdot \theta$ nothing is selected and $(s \approx t) \cdot \theta$ is strictly maximal
- 4 $(w \not\approx v) \cdot \theta$ is selected or maximal and no other literal is selected in $D \vee (w \not\approx v) \cdot \theta$
- 5 $w|_p$ is not a variable.

Resolution

Basic Superposition: Observations on *ALCHIQ* Clauses

- For all rules with more than one premise, the resolved literals have to be strictly maximal.
- Strictly maximal equation literals have comparable arguments.
- There are only 3 types of unifications in BS inferences:

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 \neg P(..) & P(..) \\
 \neg f(..) = g(..) & f(..) = h(..) \\
 \neg P(f(..)) & f(..) = g(..)
 \end{array}$$

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⇒ Communication Strategy Based on Symbol Allocation

Distributed Resolution Reasoning

Outline

- ⇒ Local reasoning method
 - Communication strategy
 - Experiments

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Communication Strategy

Allocation of Clauses to Reasoners

Based on allocation and precedence of symbols

- 1 Pick the maximal literal of the clause
- 2 Pick the top predicate of that literal
- 3 Allocate the clause to the reasoner that the predicate is allocated to
- 2b Pick the top function symbol of that literal
- 3b Allocate the clause to the reasoner that the symbol is allocated to

Example

$$C(x) \vee D(f(x)) \vee A(x)$$

allocation

symbol	reasoner
A	1
B	2
C	2
D	1
f	2
g	1

precedence

$f > g > A > B > C > D$

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allocation

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f	2
g	1

precedence

$f > g > A > B > C > D$

Communication Strategy

Allocation of Clauses to Reasoners

Based on allocation and precedence of symbols

- 1 Pick the maximal literal of the clause
 - 2 Pick the top predicate of that literal
 - 3 Allocate the clause to the reasoner that the predicate is allocated to
- 2b Pick the top function symbol of that literal
 - 3b Allocate the clause to the reasoner that the symbol is allocated to

Example

$C(x) \vee D(f(x)) \vee A(x) \rightarrow$ reasoner 1

allocation

symbol	reasoner
A	1
B	2
C	2
D	1
f	2
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$C(x) \vee D(f(x)) \vee A(x) \rightarrow$ reasoner 1 and 2

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$C(x) \vee D(f(x)) \vee A(x) \rightarrow$ reasoner 1 and 2

$C(x) \vee f(x) = g(x)$

allocation

symbol	reasoner
A	1
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D	1
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Method

Distributed Basic Superposition

Calculus: Basic Superposition

- Saturating the local clause set in every reasoner

Communication strategy: Based on maximal literal

- Every reasoner is responsible for a subset of symbols
- Every input/derived clause is allocated to
 - 1 the reasoner responsible for the top predicate of the literal (if predicate literal)
 - 2 the reasoner responsible for the top function symbol of the literal (if literal contains function)

Distributed Resolution Reasoning

Outline

- Local reasoning method
- ⇒ Communication strategy
- Experiments

Distributed Resolution Reasoning

Outline

- Local reasoning method
 - Communication strategy
- ⇒ Experiments

Experiments

Implementation

- Based on the first order reasoner SPASS
- Communication via TCP connections (completely connected at startup)
- Reasoner waits for new clauses when saturated locally
- The system terminates when one reasoner finds a proof or all are saturated
- Clauses are only send when the destination reasoner is idle

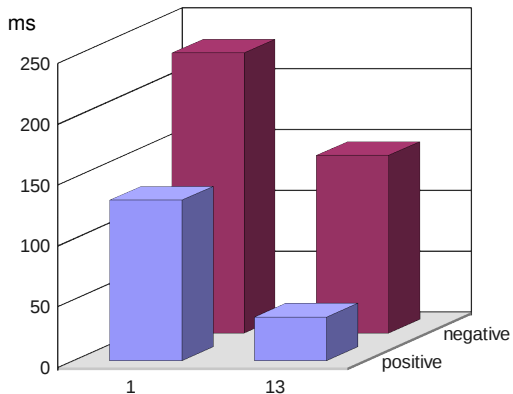
Experiments

Dataset

- SWEET (Semantic Web for Earth and Environmental Terminology) dataset published by the NASA Jet Propulsion Laboratory
- chemical ontology (chem.owl) and the ontologies that are directly or indirectly imported by chem.
- 13 ontologies liked by 34 import statements.
- The ontology network describes 480 classes and 99 individuals.
- Datatype properties replaced by object properties, nominals replaced by common concepts
- Expressivity: *SHIN*

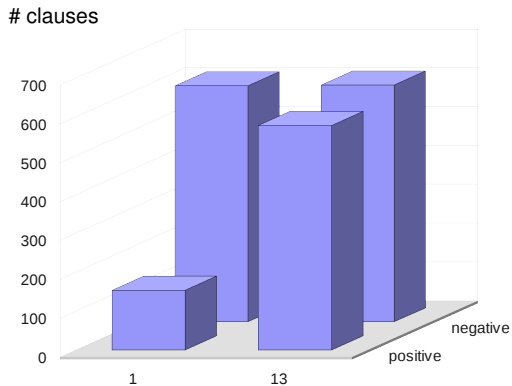
Experiments

Runtime of Positive and Negative Queries



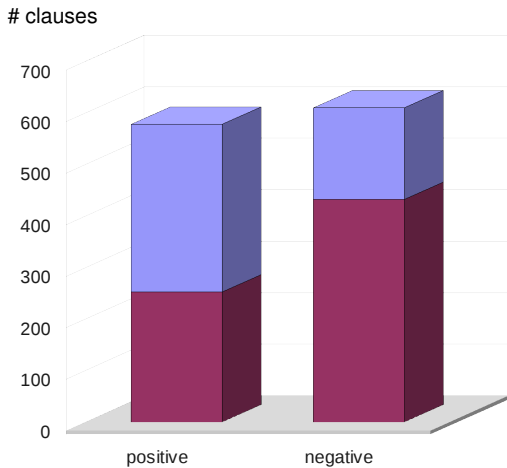
Experiments

Number of Derived Clauses



Experiments

Number of Propagated Clauses

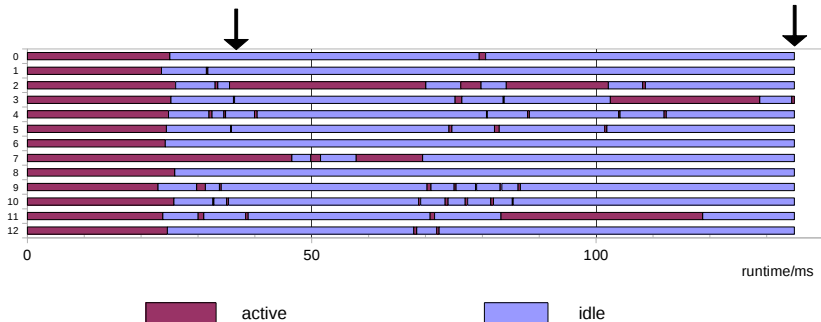


Experiments

Parallel Computation

positive queries: 60% busy

negative queries: 20% busy



Conclusion

Distributed Resolution for DL Ontologies

- The approach is complete and terminates for *ALCHIQ* ontologies
- No restriction on link axioms
- No strong restriction on distribution
- First experiments show that runtime speedup from parallel computation trades off the communication overhead.

Next Steps

- Connection on Demand
- Dynamic Allocation

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Discussion

Thank You!

Questions?

Allocating Symbols to Reasoners

Straight Forward Allocation

In ontology networks, the ontologies are usually identified by different namespaces

⇒ Allocation of namespaces to reasoners defines an allocation of symbols.

Dependency Based Allocation

- 1 Create dependency graph from axioms or clauses, each node represents a symbol
- 2 Graph partitioning (e.g. minimal edge cut)
- 3 Allocate every part (node set) to a reasoner

Communication Based Allocation

- 1 Allocate every symbol to a different reasoner
- 2 Create dependency graph based on communication
- 3 Graph partitioning, ...

Redundancy

Avoiding Redundant Inferences and Clauses

The communication strategy occasionally allocates a clause to two different reasoners.

(i.e. clauses with maximal literal $P(f(x))$ and different allocation of P and f)

- A clause is never allocated to more than two reasoners
- Duplication of clauses does not duplicate inferences
- Application of reduction rules is restricted by distributing the clause sets.
- e.g. $a \vee b \vee c$ is redundant if $a \vee b$ given
- if the two clauses are allocated to different reasoners, the redundancy is not detected

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